

Technical data Actuator controls

General information

AC 01.2 actuator controls for controlling multi-turn actuators of the SA/SAR .1, SA/SAR .2 type ranges and part-turn actuators of the SQ/SQR .2 type range.

Features and functions

Power supply	Standard voltages AC:																																																
	<table><tr><td colspan="12">3-phase AC</td></tr><tr><td colspan="12">Voltages/frequencies</td></tr><tr><td>Volt</td><td>220</td><td>230</td><td>380</td><td>380</td><td>400</td><td>400</td><td>415</td><td>440</td><td>460</td><td>480</td><td>500</td></tr><tr><td>Hz</td><td>60</td><td>50</td><td>50</td><td>60</td><td>50</td><td>60</td><td>50</td><td>60</td><td>60</td><td>60</td><td>50</td></tr></table>	3-phase AC												Voltages/frequencies												Volt	220	230	380	380	400	400	415	440	460	480	500	Hz	60	50	50	60	50	60	50	60	60	60	50
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Permissible voltage deviation: On request																																																	
External supply of the electronics (option)	24 V DC: +20 %/-15 % Current consumption: Basic version approx. 250 mA, with options up to 500 mA For external electronics supply, the power supply of integral controls must have an enhanced isolation against mains voltage in compliance with IEC 61010-1 and the output power be limited to 150 VA.																																																
Current consumption	Current consumption of the actuator controls depending on mains voltage: For permissible variation of mains voltage of ±10 %: 100 to 120 V AC = max. 740 mA 208 to 240 V AC = max. 400 mA 380 to 500 V AC = max. 250 mA 515 V AC = max. 200 mA For permissible variation of mains voltage of ±30 %: 100 to 120 V AC = max. 1,200 mA 208 to 240 V AC = max. 750 mA 380 to 500 V AC = max. 400 mA 515 to 690 V AC= max. 400 mA																																																
Overvoltage category	Category III according to IEC 60364-4-443																																																
Rated power	Actuator controls are designed for nominal motor power, refer to Electrical data pertaining to the actuator																																																

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Features and functions		
Switchgear	Standard:	Reversing contactors (mechanically and electrically interlocked) for AUMA power classes A1/A2
	Options:	Reversing contactors (mechanically and electrically interlocked) for AUMA power class A3 Thyristor unit for mains voltage up to 500 V AC (recommended for modulating actuators) for AUMA power classes B1, B2 and B3
	The reversing contactors are designed for a lifetime of 2 million starts. For applications requiring a high number of starts, we recommend the use of thyristor units. For the assignment of AUMA power classes, please refer to Electrical data on actuator	
Control inputs	6 digital inputs: OPEN, STOP, CLOSE, EMERGENCY (via opto-isolator, thereof OPEN, STOP, CLOSE with one common and EMERGENCY without common, respect minimum pulse duration for modulating actuators).	
Control voltage/current consumption for control inputs	Standard:	24 V DC, current consumption: approx. 10 mA per input
	Options:	48 V DC, current consumption: approx. 7 mA per input 60 V DC, current consumption: approx. 9 mA per input 100 – 125 V DC, current consumption: approx. 15 mA per input 100 – 120 V AC, current consumption : approx. 15 mA per input
	All input signals must be supplied with the same potential.	
Status signals (output signals)	Standard:	6 programmable output contacts: 5 potential-free NO contacts with one common, max. 250 V AC, 1 A (resistive load) Default configuration: End position CLOSED, end position OPEN, selector switch REMOTE, fault CLOSE, torque fault OPEN 1 potential-free change-over contact, max. 250 V AC, 5 A (resistive load) Default configuration: Collective fault signal (torque fault, phase failure, motor protection tripped) - Analogue output signal for position feedback - Galvanically isolated position feedback 0/4 – 20 mA (load max. 500 Ω)
	Options:	6 programmable output contacts: 5 change-over contacts with one common, max. 250 V AC, 1 A (resistive load), 1 potential-free change-over contact, max. 250 V AC, 5 A (resistive load) 12 programmable output contacts: 10 potential-free NO contacts, 5 with one common each, max. 250 V AC, 1 A (resistive load), 2 potential-free change-over contacts, max. 250 V AC, 5 A (resistive load) 6 programmable output contacts: 6 potential-free change-over contacts without one common, per contact max. 250 V AC, 5 A (resistive load) 10 programmable output contacts: 10 potential-free change-over contacts without one common, per contact max. 250 V AC, 5 A (resistive load) 6 programmable output contacts: 4 mains failure proof potential-free NO contacts with one common, max. 250 V AC, 1 A (resistive load), 1 potential-free NO contact, max. 250 V AC, 1 A (resistive load), 1 potential-free change-over contact, max. 250 V AC, 5 A (resistive load) 6 programmable output contacts: 4 mains failure proof potential-free NO contacts, max. 250 V AC, 5 A (resistive load), 2 potential-free change-over contacts, max. 250 V AC, 5 A (resistive load), 12 programmable output contacts: 8 mains failure proof potential-free NO contacts, max. 250 V AC, 1 A (resistive load), 2 potential-free NO contacts, max. 250 V AC, 1 A (resistive load), 2 potential-free change-over contacts, max. 250 V AC, 5 A (resistive load) 12 programmable output contacts: 8 mains failure proof potential-free NO contacts, max. 250 V AC, 5 A (resistive load), 4 potential-free change-over contacts, max. 250 V AC, 5 A (resistive load), All output signals must be supplied with the same potential.

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Features and functions	
with additional output signals (option)	Additional, binary output signals (only available in combination with additional input signals (option)) 6 programmable output contacts: 5 potential-free NO contacts with one common, max. 250 V AC, 1 A (resistive load) Default configuration: End position CLOSED, end position OPEN, selector switch REMOTE, torque fault CLOSE, torque fault OPEN 1 potential-free change-over contact, max. 250 V AC, 5 A (resistive load) Default configuration: Collective fault signal (torque fault, phase failure, motor protection tripped) 6 programmable output contacts: 5 potential-free change-over contacts with one common, max. 250 V AC, 1 A (resistive load) 1 potential-free change-over contact, max. 250 V AC, 5 A (resistive load) 6 programmable output contacts: 6 potential-free change-over contacts without one common, max. 250 V AC, 5 A (resistive load) 6 programmable output contacts: 4 mains failure proof potential-free NO contacts with one common, max. 250 V AC, 1 A (resistive load), 1 potential-free NO contact, max. 250 V AC, 1 A (resistive load), 1 potential-free change-over contact, max. 250 V AC, 5 A (resistive load) 6 programmable output contacts: 4 mains failure proof potential-free NO contacts, max. 250 V AC, 5 A (resistive load), 2 potential-free change-over contacts, max. 250 V AC, 5 A (resistive load), All binary output signals must be supplied with the same potential. - Analogue output signal for position feedback - Galvanically isolated position feedback 0/4 – 20 mA (load max. 500 Ω)
Voltage output	Standard: Auxiliary voltage 24 V DC: max. 100 mA for supply of control inputs, galvanically isolated from internal voltage supply.
	Option: Auxiliary voltage 115 V AC: max. 30 mA for supply of control inputs, galvanically isolated from internal voltage supply (Not possible in combination with PTC tripping device)
Analogue output (option)	2 analogue outputs: With position transmitter option: Output of travel and torque as continuous values between 0/4 and 20 mA
Analogue input (option)	2 analogue inputs: With positioner/process controller option: Input of actual position value/actual process value as continuous values of 0/4 – 20 mA.
Local controls	Standard: - Selector switch: LOCAL - OFF - REMOTE (lockable in all three positions) - Push buttons OPEN, STOP, CLOSE, RESET - Local STOP The actuator can be stopped via push button STOP of local controls if the selector switch is in position REMOTE. (Not activated when leaving the factory.) 6 indication lights: - End position and running indication CLOSED (yellow), torque fault CLOSE (red), motor protection tripped (red), torque fault OPEN (red), end position and running indication OPEN (green), Bluetooth (blue) - Graphic LC display: illuminated
	Option: - Special colours for the indication lights: - End position CLOSED (green), torque fault CLOSE (blue), torque fault OPEN (yellow), motor protection tripped (violet), end position OPEN (red)
Bluetooth Communication interface	Bluetooth Class II Chip, Version 2.1: With a range up to 10 m in industrial environments supports the SSP Bluetooth profile (Serial Port Profile). Required accessories: - AUMA CDT (Commissioning and Diagnostic Tool for Windows-based PC) - AUMA Assistant App (Commissioning and Diagnostic Tool)

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Features and functions		
Application functions	Standard:	- Selectable type of seating, limit or torque seating for end position OPEN and end position CLOSED - Torque by-pass: Adjustable duration (with adjustable peak torque during start-up time) - Start and end of stepping mode as well as ON and OFF times can be set individually for directions OPEN and CLOSE, 1 to 1,800 seconds - Any 8 intermediate positions: can be set between 0 and 100 %, reaction and signal behaviour programmable - Running indication blinking: can be set
	Options:	- Positioner - Position setpoint via analogue input 0/4 – 20 mA - Programmable behaviour on loss of signal - Automatic adaptation of dead band (adaptive behaviour selectable) - Split range operation - MODE input for selecting between OPEN-CLOSE and setpoint control - PID process controller: with adaptive positioner, via 0/4 – 20 mA analogue inputs for process setpoint and actual process value - Automatic deblocking: Up to 5 operation trials, travel time in opposite direction can be set - Static and dynamic torque recording for both rotation directions with torque measurement flange as additional accessory
Safety functions	Standard:	- EMERGENCY operation (programmable behaviour) - Digital input: Low active - Reaction can be selected: Stop, run to end position CLOSED, run to end position OPEN, run to intermediate position - Torque monitoring can be by-passed during EMERGENCY operation - Thermal protection can be by-passed during EMERGENCY operation (only in combination with thermoswitch within actuator, not with PTC thermistor).
	Options:	- Enabling local controls via digital input Enable LOCAL. Thus, actuator operation can be enabled or disabled via push buttons on local controls. - Interlock for main/by-pass valve: Enabling the operation commands OPEN or CLOSE via two digital inputs - EMERGENCY Stop push button (latching): Interrupts electrical operation, irrespective of the selector switch position - PVST (Partial Valve Stroke Test): programmable to check the function of both actuator and actuator controls: Direction, stroke, operation time, reversing time
Monitoring functions		- Valve overload protection: Adjustable, results in switching off and generates fault signal - Motor temperature monitoring (thermal monitoring): Results in switching off and generates fault signal - Monitoring the heater within actuator: Generates warning signal - Monitoring of permissible on-time and number of starts: Adjustable, generates warning signal - Operating time monitoring: Adjustable, generates warning signal - Phase failure monitoring: Results in switching off and generates fault signal - Automatic correction of rotation direction upon wrong phase sequence (3-ph AC current)
Diagnostic functions		- Electronic device ID with order and product data - Operating data logging: A resettable counter and a lifetime counter each for: - Motor running time, number of starts, torque switch trippings in end position CLOSED, limit switch trippings in end position CLOSED, torque switch trippings in end position OPEN, limit switch trippings in end position OPEN, torque faults CLOSE, torque faults OPEN, motor protection trippings - Time-stamped event report with history for setting, operation and faults - Status signals according to NAMUR recommendation NE 107: "Failure", "Function check", "Out of specification", "Maintenance required" - Torque characteristics (for version with MWG in actuator): 3 torque characteristics (torque-travel characteristic) for opening and closing directions can be saved separately. - Torque characteristics stored can be shown on the display.
Motor protection evaluation	Standard:	Monitoring the motor temperature in combination with thermoswitches within actuator motor
	Options:	- Thermal overload relay in controls combined with thermoswitches within actuator - PTC tripping device in combination with PTC thermistors within actuator motor
Electrical connection	Standard:	AUMA plug/socket connector with screw-type connection
	Option:	Gold-plated control plug (sockets and plugs)

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Features and functions		
Threads for cable entries	Standard:	Metric threads
	Options:	• Pg-threads, NPT-threads, G-threads • Terminals or crimp-type connection
Wiring diagram (basic version)	TPCA-0A1-1C1-A000 TPA00R1AA-0A1-000	

Further options for Non-intrusive version with MWG in the actuator	
Setting of limit and torque switching via local controls	
Torque feedback signal	Galvanically isolated analogue output 0/4 – 20 mA (load max. 500 Ω).
Wiring diagram (basic version)	TPCA-0A1-1C1-A000 TPA00R100-0I1-000

Service conditions		
Use	Indoor and outdoor use permissible	
Mounting position	Any position	
Installation altitude	≤ 2 000 m above sea level > 2,000 m above sea level, on request	
Ambient temperature	Standard:	–30 °C to +70 °C
		–40 °C to +70 °C
	Options:	–60 °C to +60 °C, extreme low temperature version Low temperature versions incl. heating system for connection to external power supply 230 V AC or 115 V AC, or internal version 400 V AC.
Humidity	Up to 100 % relative humidity across the entire permissible temperature range	
Enclosure protection in accordance with IEC 60529	Standard:	IP68
	Option:	Terminal compartment additionally sealed against interior of actuator controls (double sealed)
	According to AUMA definition, enclosure protection IP68 meets the following requirements: • Depth of water: Maximum 8 m head of water • Continuous immersion in water: maximal 96 hours • Up to 10 operations during immersion • Modulating duty is not possible during immersion.	
Pollution degree according to IEC 60664-1	Pollution degree 4 (when closed), pollution degree 2 (internal)	
Vibration resistance according to IEC 60068-2-6	1 g, from 10 Hz to 200 Hz Resistant to vibration during start-up or for failures of the plant. However, a fatigue strength may not be derived from this. (Not valid in combination with gearboxes)	
Corrosion protection	Standard:	KS: Suitable for use in areas with high salinity, almost permanent condensation, and high pollution.
	Option:	KX: Suitable for use in areas with extremely high salinity, permanent condensation, and high pollution.
Coating	Double layer powder coating Two-component iron-mica combination	
Colour	Standard:	AUMA silver-grey (similar to RAL 7037)
	Option:	Available colours on request

Accessories	
Wall bracket	For actuator controls mounted separately from the actuator, including plug/socket connector. Connecting cable on request. Recommended for high ambient temperatures, difficult access, or in case of heavy vibration during service. Cable length between actuator and actuator controls is max. 100 m. An MWG is required for position feedback.
Programming software	AUMA CDT (Commissioning and Diagnostic Tool for Windows-based PC) AUMA Assistant App (Commissioning and Diagnostic Tool)
Torque measurement flange DMF	Accessory for torque measurement for SA/SAR 07.2 – SA/SAR 16.2

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Further information	
Weight	Approx. 7 kg (with AUMA plug/socket connector)
EU Directives	Machinery Directive 2006/42/EC Low Voltage Directive 2014/35/EU EMC Directive 2014/30/EU RoHS Directive 2011/65/EU
Reference documents	Dimensions SA 07.2 – SA 16.2/SAR 07.2 – SAR 16.2 with AC 01.2 Dimensions SQ 05.2 – SQ 14.2/SQR 05.2 – SQR 14.2 with AC 01.2 Electrical data SA 07.2 – SA 16.2/SAR 07.2 – SAR 16.2 Electrical data SQ 05.2 – SQ 14.2/SQR 05.2 – SQR 14.2